

Lecture 11

Integration

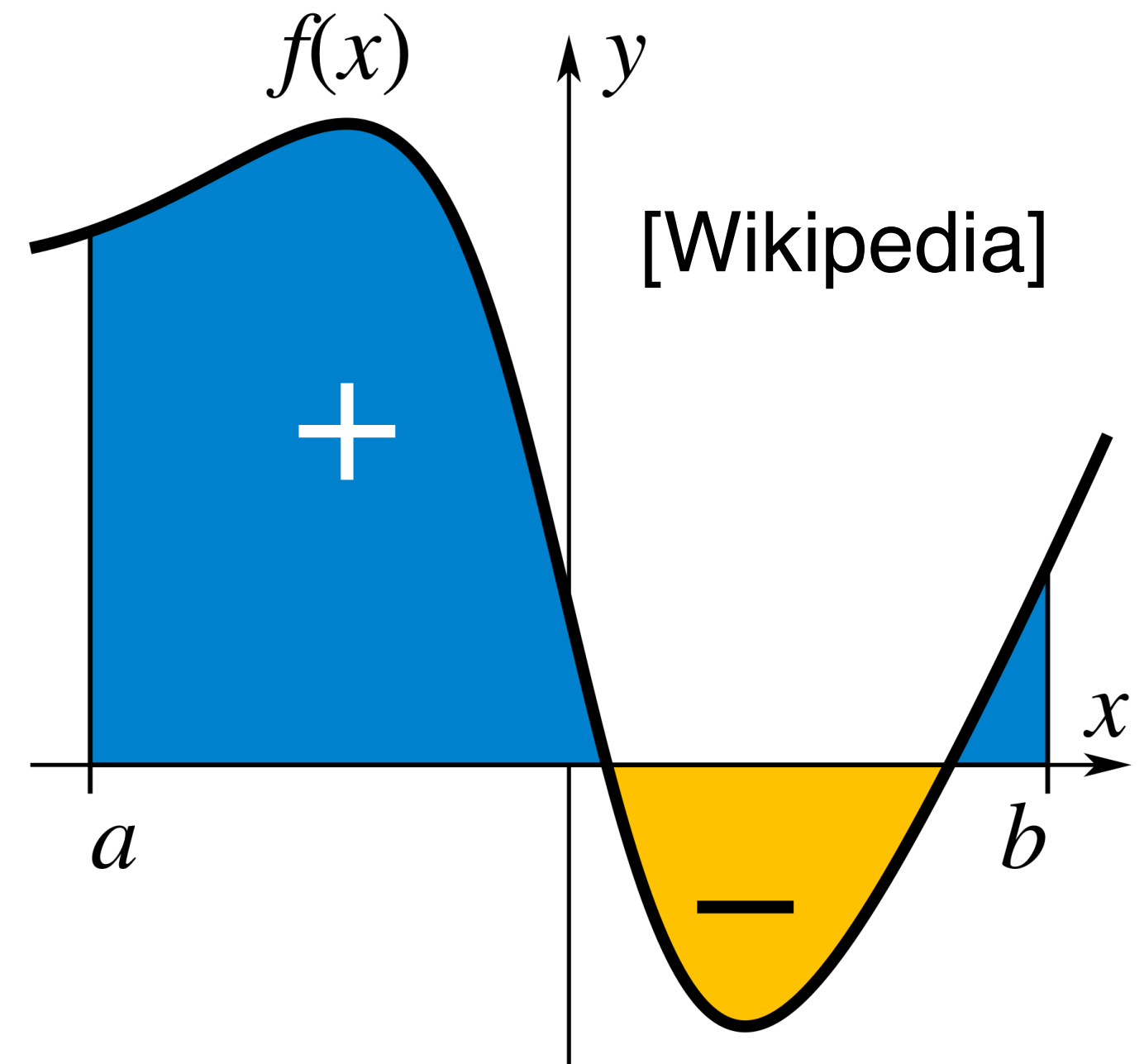
Quadrature and Monte Carlo methods

**CS328 - Numerical Methods for
Visual Computing and Machine Learning**

Prof. Wenzel Jakob

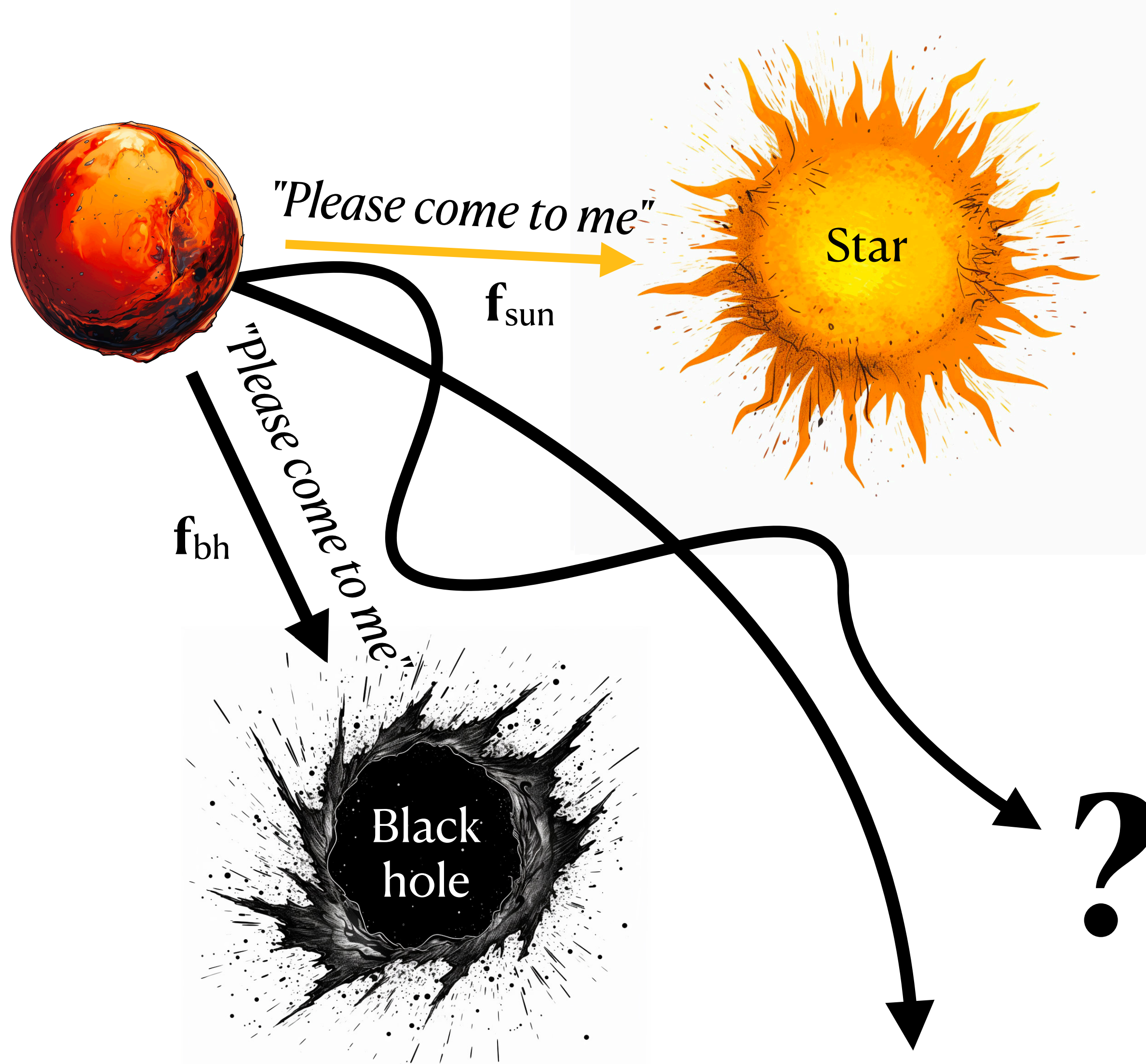
Definite integrals

$$\int_a^b f(x) dx$$



Why do integrals arise?

.. for many reasons, but here are two examples of physical processes



Velocity is the time derivative of **position**

$$\mathbf{v}(t) = \frac{\partial}{\partial t} \mathbf{x}(t)$$

Acceleration is the time derivative of **velocity**

$$\mathbf{a}(t) = \frac{\partial}{\partial t} \mathbf{v}(t)$$

Newton's 2nd law relates **acceleration** to **forces**:

$$\mathbf{a}(t) = \frac{\mathbf{f}(t)}{m} = \frac{\mathbf{f}_{\text{sun}}(t) + \mathbf{f}_{\text{bh}}(t)}{m}$$

Mass of the planet

Why do integrals arise?

.. for many reasons, but here are two examples of physical processes

Wanted: position as a function of time

$$\mathbf{x}(t)$$



$$\frac{d}{dt}$$

$$\frac{d}{dt}$$

Velocity is the time derivative of **position**

$$\mathbf{v}(t) = \frac{\partial}{\partial t} \mathbf{x}(t)$$

Acceleration is the time derivative of **velocity**

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Mass of the planet

Physical equation models the evolution of the world as a *time average*.

This average is not discrete but has *infinite resolution*, hence an integral must be used to simulate physics.

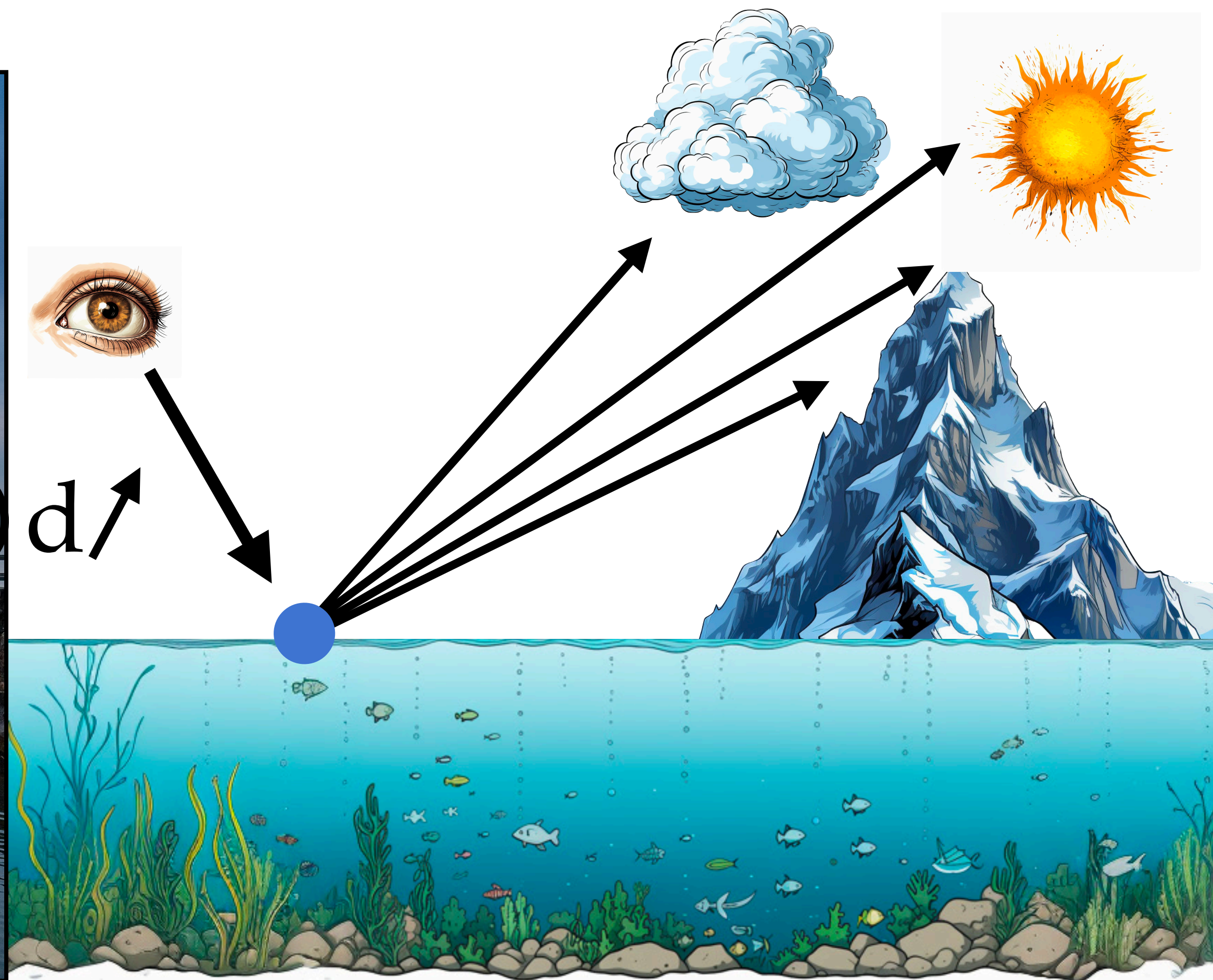
Why do integrals arise?

.. for many reasons, but here are two examples of physical processes

Describes properties of the material

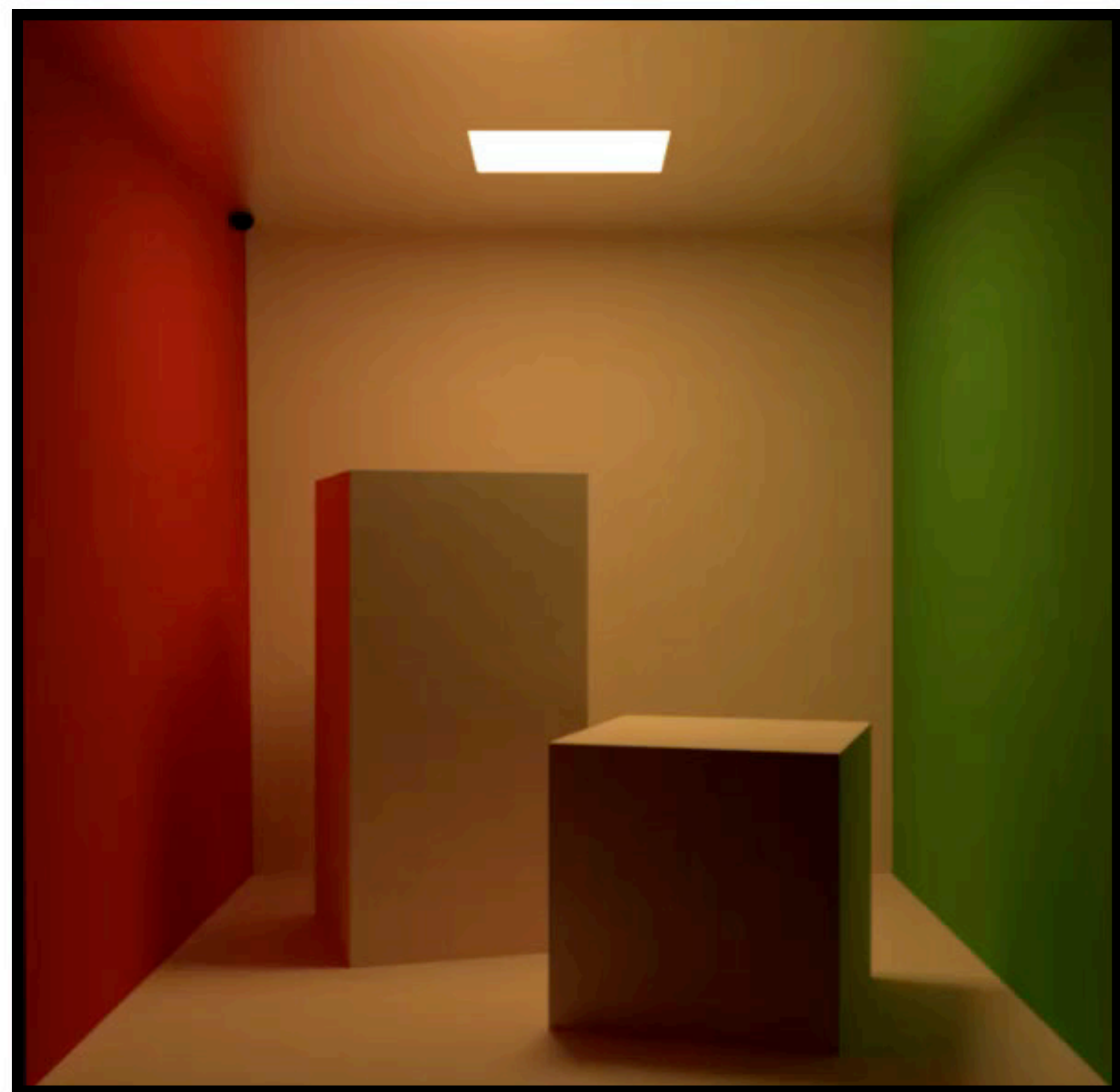
$$\text{Light}(\text{eye}) = \int \text{Light}(\text{point}) f(\text{material}) d\text{area}$$

The light reflected by a point is a *weighted average* of the arriving light. This average has infinite resolution and must be computed using an integral.



[Lake Geneva from Chillon Castle, [Wikimedia commons](#)]

Computing integrals to create images

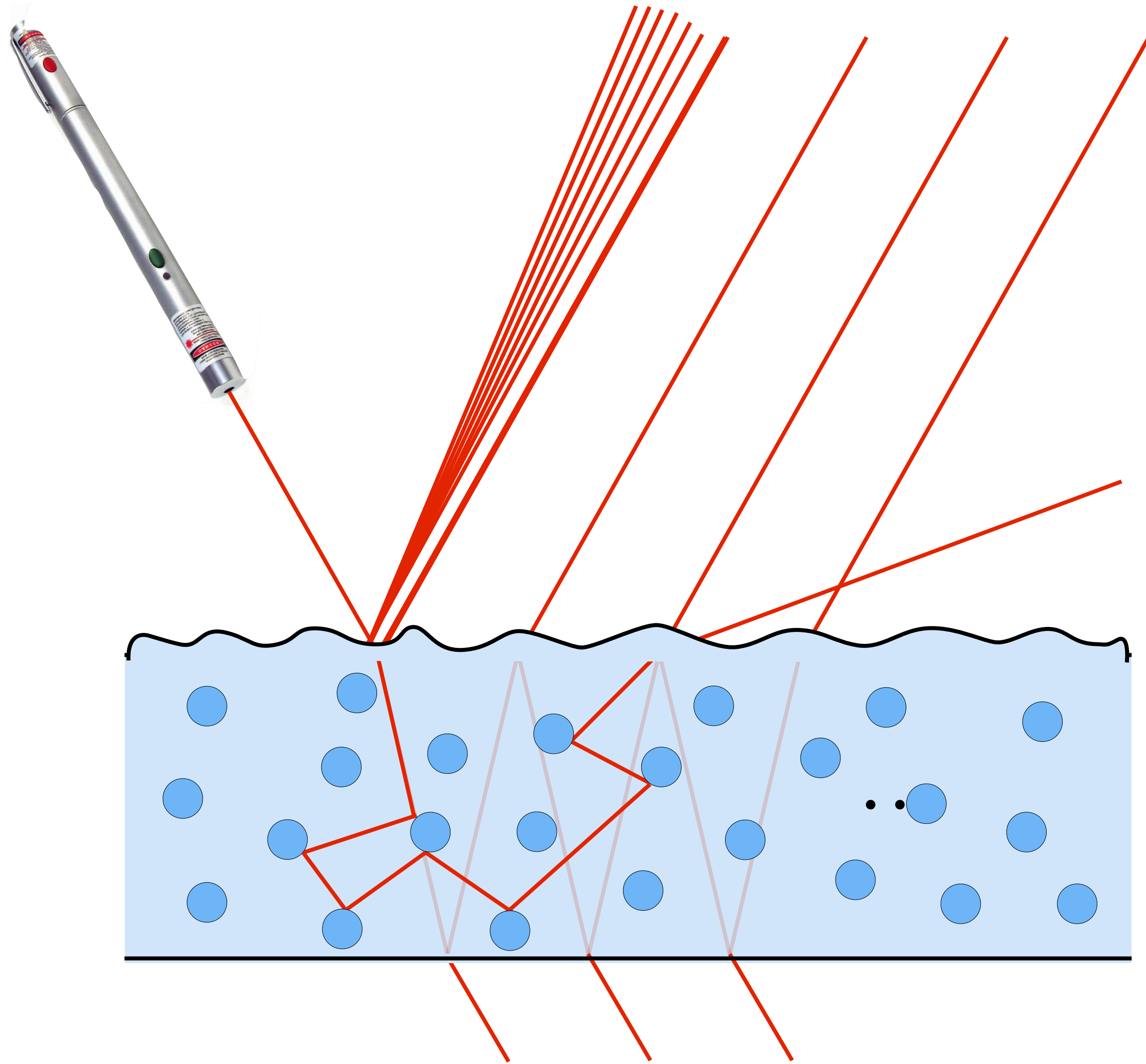


$$\int_{\mathcal{S}^2} \text{[Scene View]} \cdot \text{[Light Source]} d\omega$$

$$= \int_{\mathcal{S}^2} \text{[Final Pixel Color]} d\omega = \text{[Red Square]}$$

Final pixel color

Various types of materials and the effects they produce



[Rendered image made using Mitsuba Renderer]

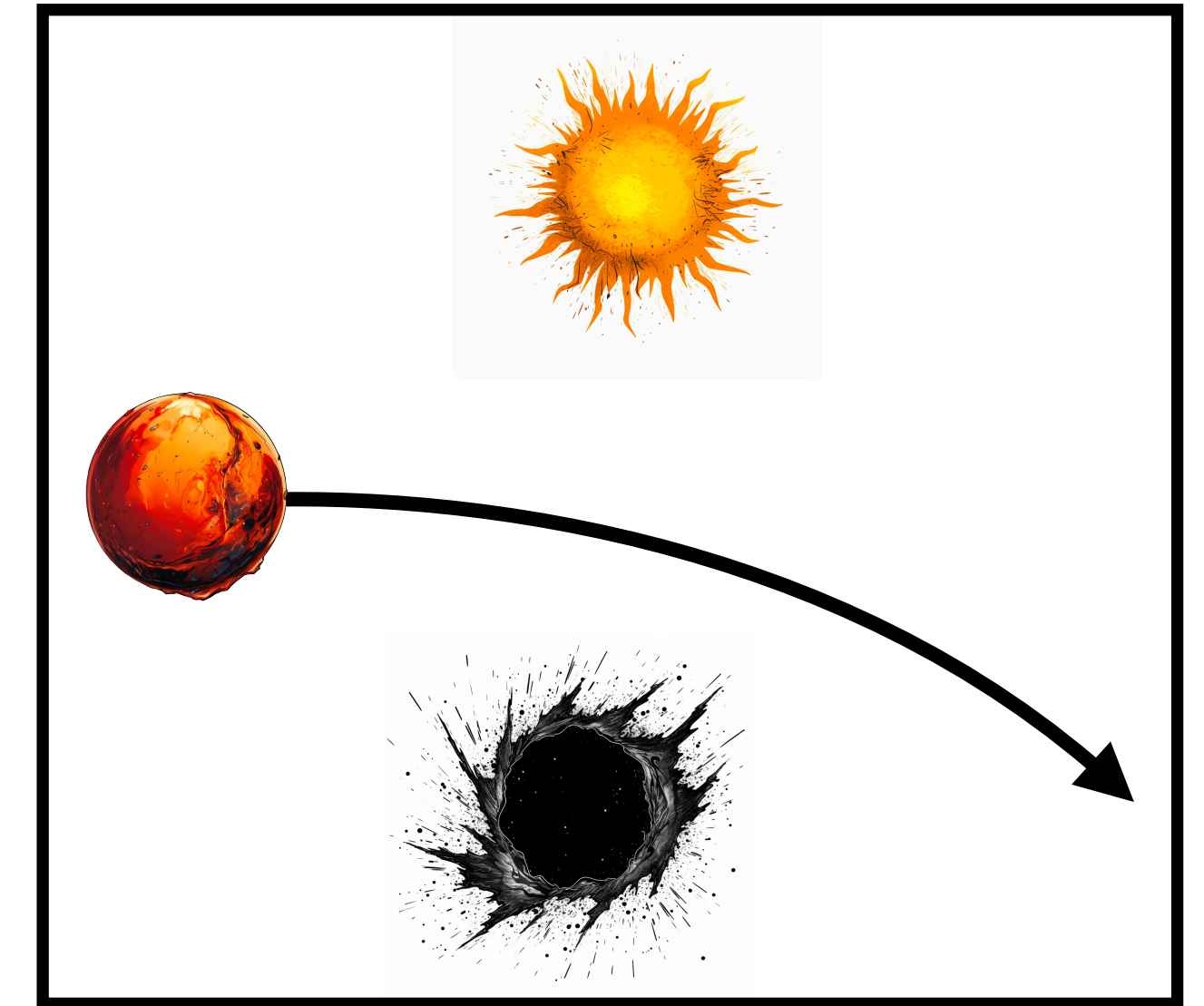


Dawn of the Planet of the Apes , © 2013 Twentieth Century Fox Film Corporation. All Rights Reserved.
Image provided by Weta Digital.

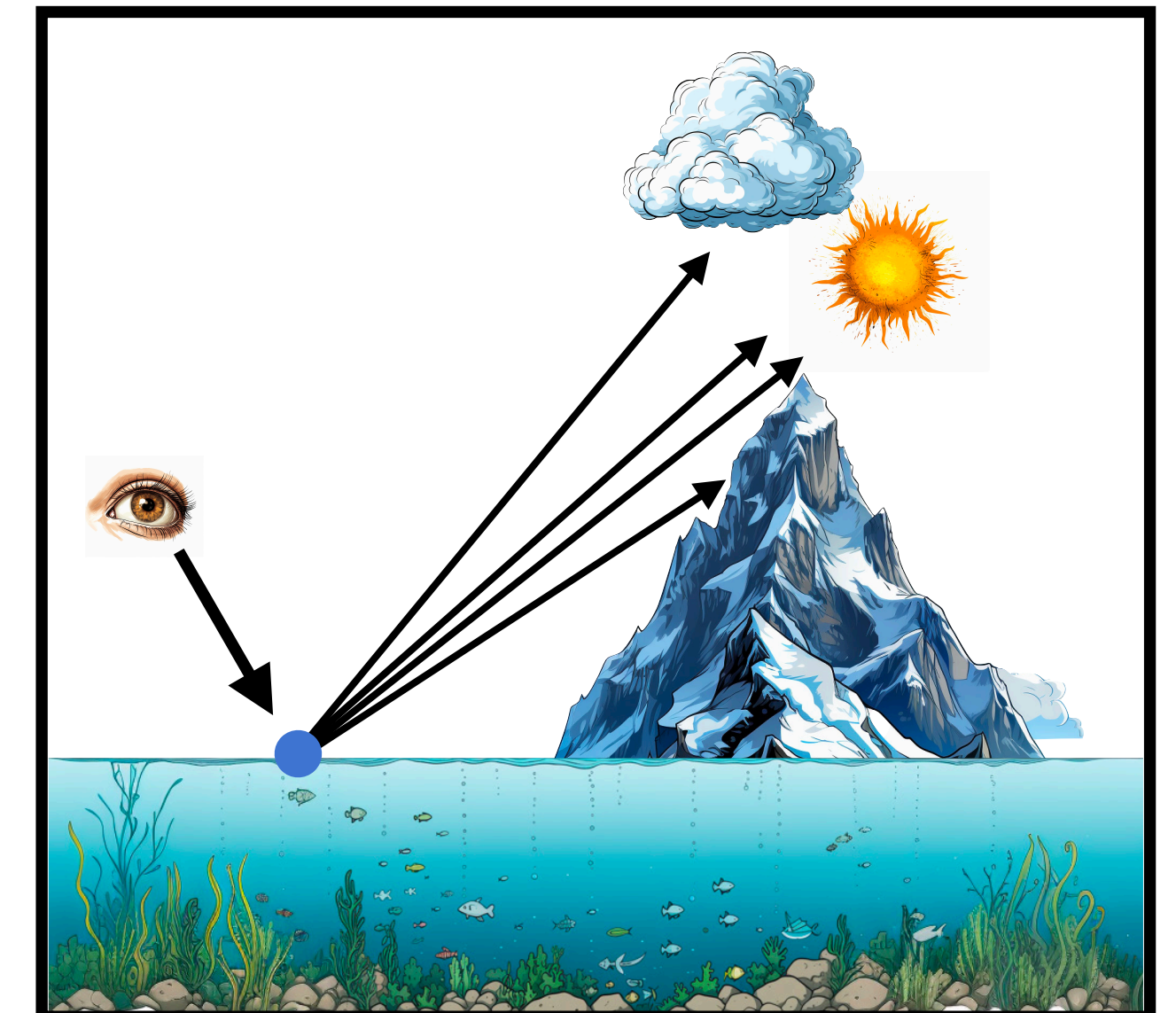
Today's topics

- Why is integration harder than differentiation?
- Approach 1: Quadrature
 - Riemann integration
 - Rules: midpoint, trapezoid, Simpson.
 - The curse of dimensionality
- Approach 2: Monte Carlo
 - History
 - Computing integrals using random numbers
 - Importance sampling

*Low
dimensional
integration*



*High
dimensional
integration*



Integration, MATH-101 style

1. Find **antiderivative** using “rules of the game”

$$F(x) := \int f(x) dx$$

(indefinite integral)

2. Apply fundamental theorem of calculus

$$\int_a^b f(x) dx = F(b) - F(a)$$

(definite integral)

The rules of the game, aka. calculus

Rules for specific functions:

$$\int x^a dx = \frac{x^{a+1}}{a+1} + C \quad (\text{for } a \neq -1)$$

$$\int \frac{1}{x} dx = \ln |x| + C \quad \int e^{ax} dx = \frac{1}{a} e^{ax} + C$$

$$\int \sin x dx = -\cos x + C$$

Meta-rules: integration by parts:

$$\begin{aligned} \int_a^b u(x)v'(x) dx &= [u(x)v(x)]_a^b - \int_a^b u'(x)v(x) dx \\ &= u(b)v(b) - u(a)v(a) - \int_a^b u'(x)v(x) dx \end{aligned}$$

Integration versus differentiation

Differentiation

Analytic &
numerical
approaches

OK



$$\int f(x) dx$$

$$f(x)$$

$$f'(x)$$

Integration

Analytic
approaches

**almost
always fail**

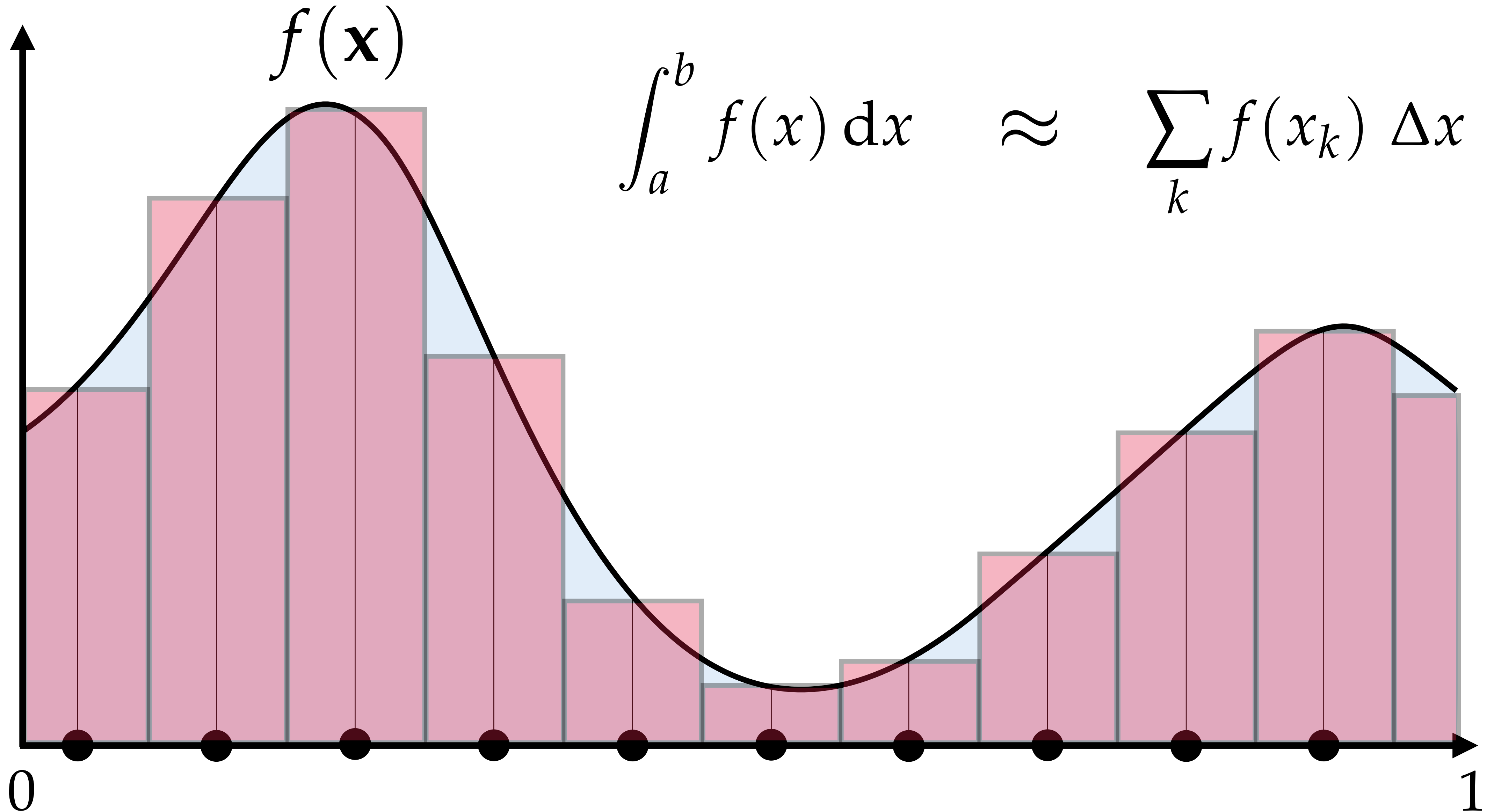


Numerical
approaches

OK



Approximating integrals using Riemann sums



Quadrature

- **High level idea:**
 - Build an approximation of the original function (*Riemann sum: piecewise constant*)
 - Must be possible to create/fit this approximation from a function evaluations
 - Approximation must have an *analytic integral*.
 - Use integral of the approximation as approximation of the *original* analytic integral.
- **Two flavors:**
 - **Quadrature rule:** applies to small part of the function
 - **Composite quadrature:** repeatedly applies the rule to integrate the *entire* function.

Midpoint rule

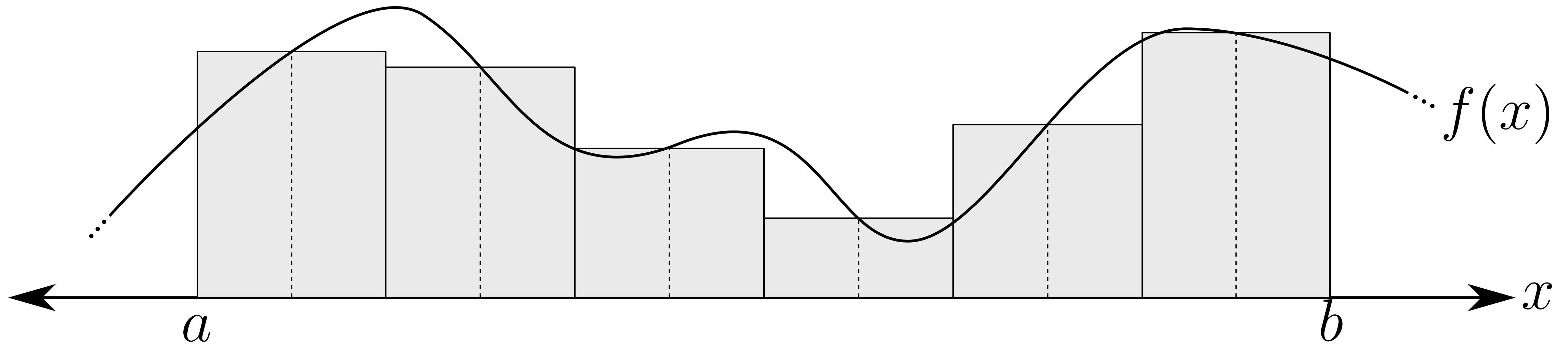
$$\int_a^b f(x) dx \approx (b - a) f\left(\frac{a + b}{2}\right)$$

$$f\left(\frac{a + b}{2}\right)$$



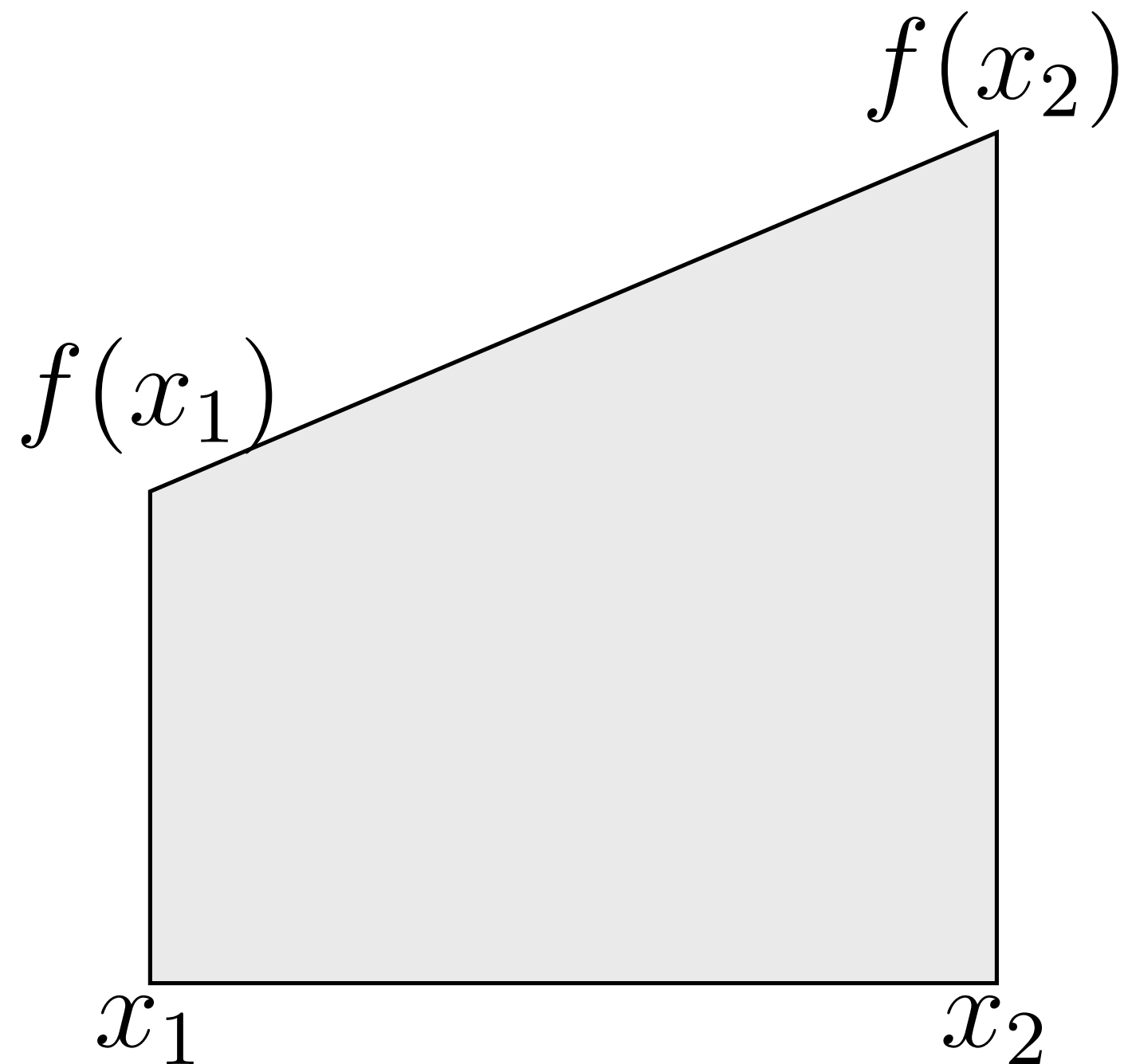
Composite midpoint rule

$$\int_a^b f(x) dx \approx \sum_{i=1}^k f\left(\frac{x_{i+1} + x_i}{2}\right) \Delta x$$



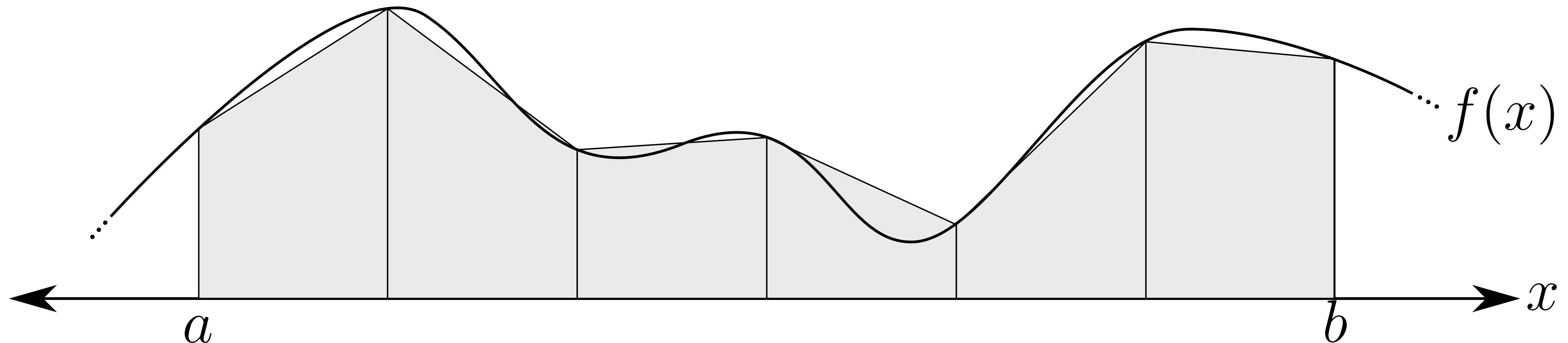
Trapezoid rule

$$\int_a^b f(x) dx \approx (b - a) \frac{f(a) + f(b)}{2}$$



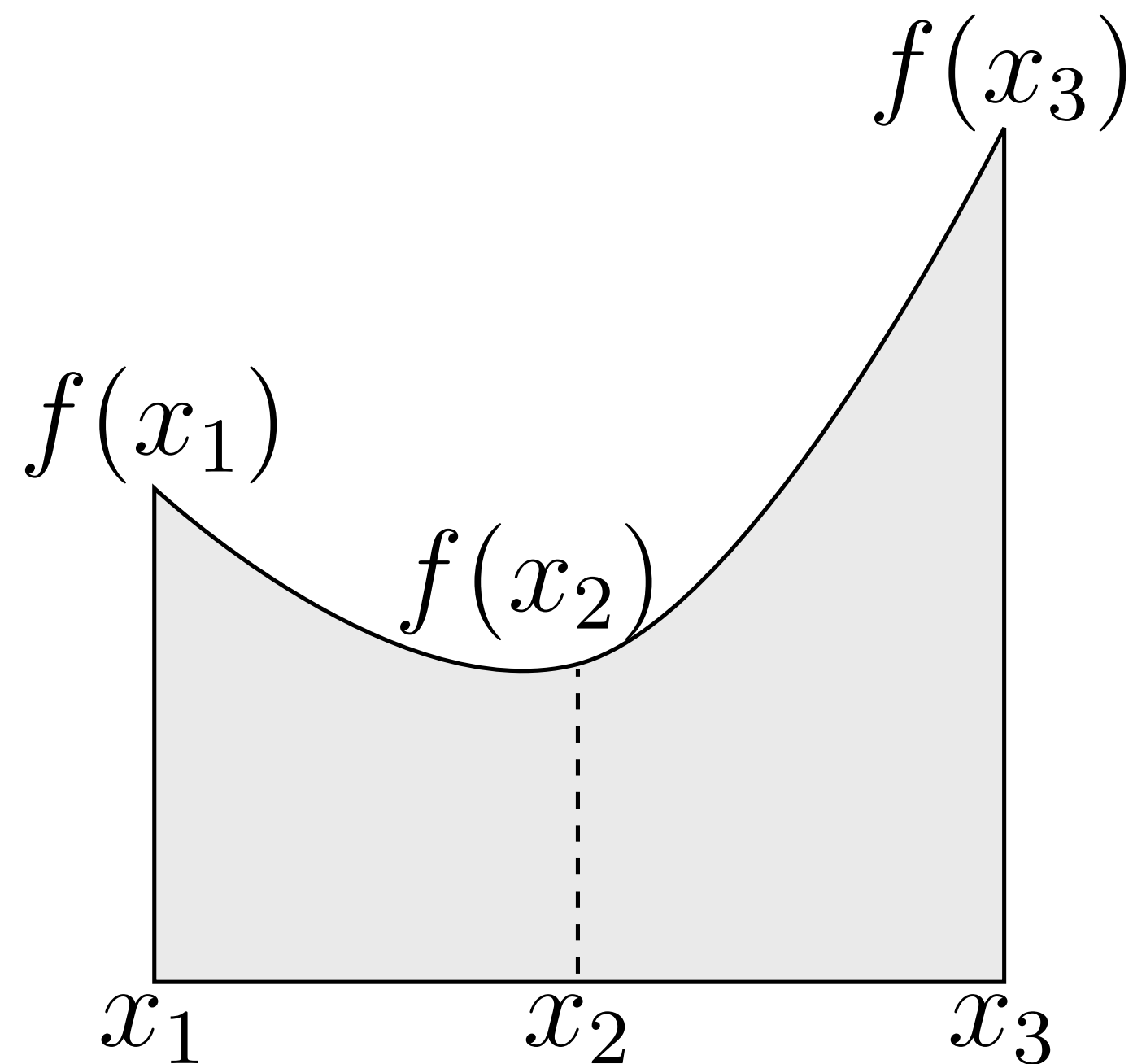
Composite trapezoid rule

$$\int_a^b f(x) dx \approx \sum_{i=1}^k \left(\frac{f(x_i) + f(x_{i+1})}{2} \right) \Delta x$$
$$= \Delta x \left(\frac{1}{2} f(a) + f(x_1) + \dots + f(x_{k-1}) + \frac{1}{2} f(b) \right)$$



Simpson's rule

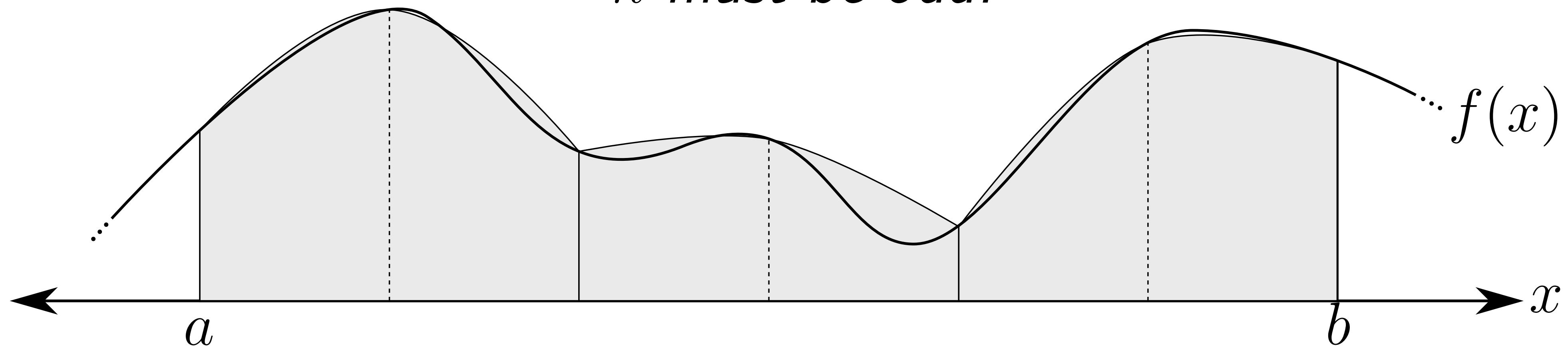
$$\int_a^b f(x) dx \approx \frac{b-a}{6} \left(f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right)$$



Composite Simpson's rule

$$\int_a^b f(x) dx \approx \frac{\Delta x}{3} \left[f(a) + 2 \sum_{i=1}^{n-2-1} f(x_{2i}) + 4 \sum_{i=1}^{n/2} f(x_{2i-1}) + f(b) \right]$$
$$= \frac{\Delta x}{3} [f(a) + 4f(x_1) + 2f(x_2) + \cdots + 4f(x_{n-1}) + f(b)]$$

n must be odd!



Demo time

Adaptive quadrature

High-level idea

```
def integrate(f, a, b):
```

```
    i_t = trapezoid(f, a, b)
```

```
    i_s = simpson(f, a, b)
```

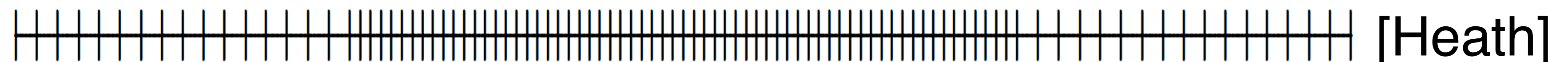
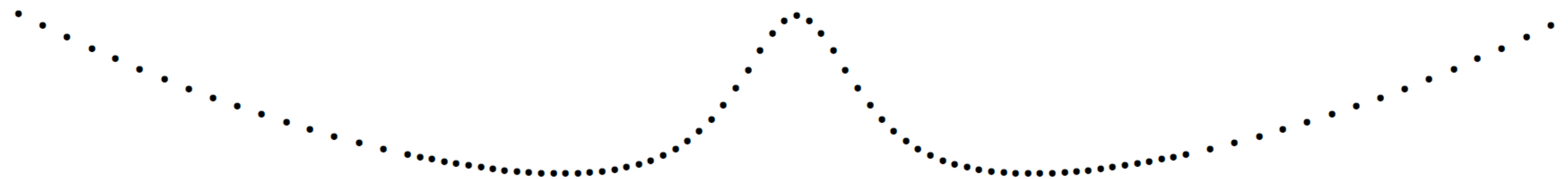
```
    if abs(i_s - i_t) >  $\epsilon$  * abs(i_t):
```

```
        mid = (a + b) / 2
```

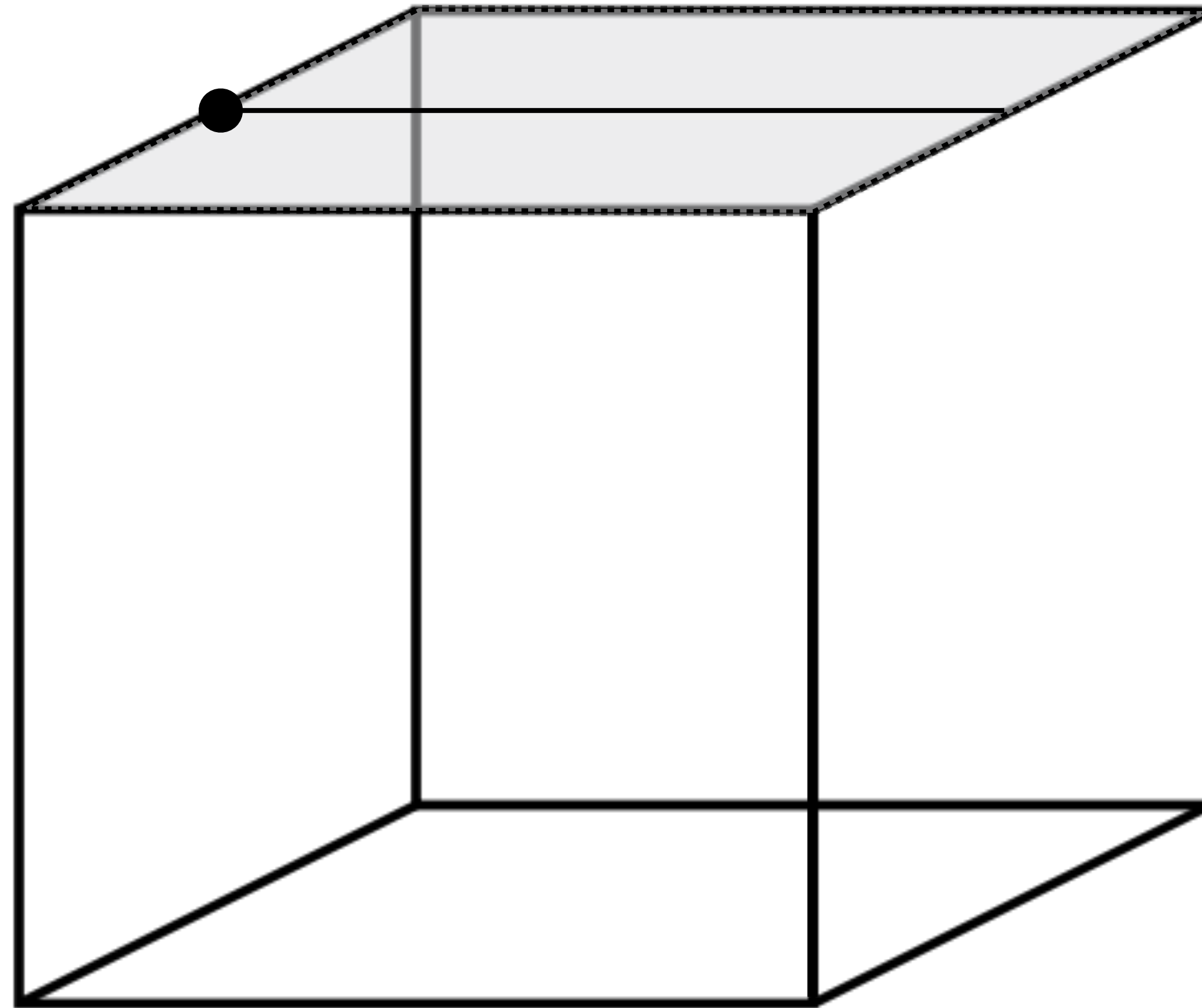
```
        return integrate(f, a, mid) + integrate(f, mid, b)
```

```
    else:
```

```
        return i_s
```



Higher-dimensional quadrature

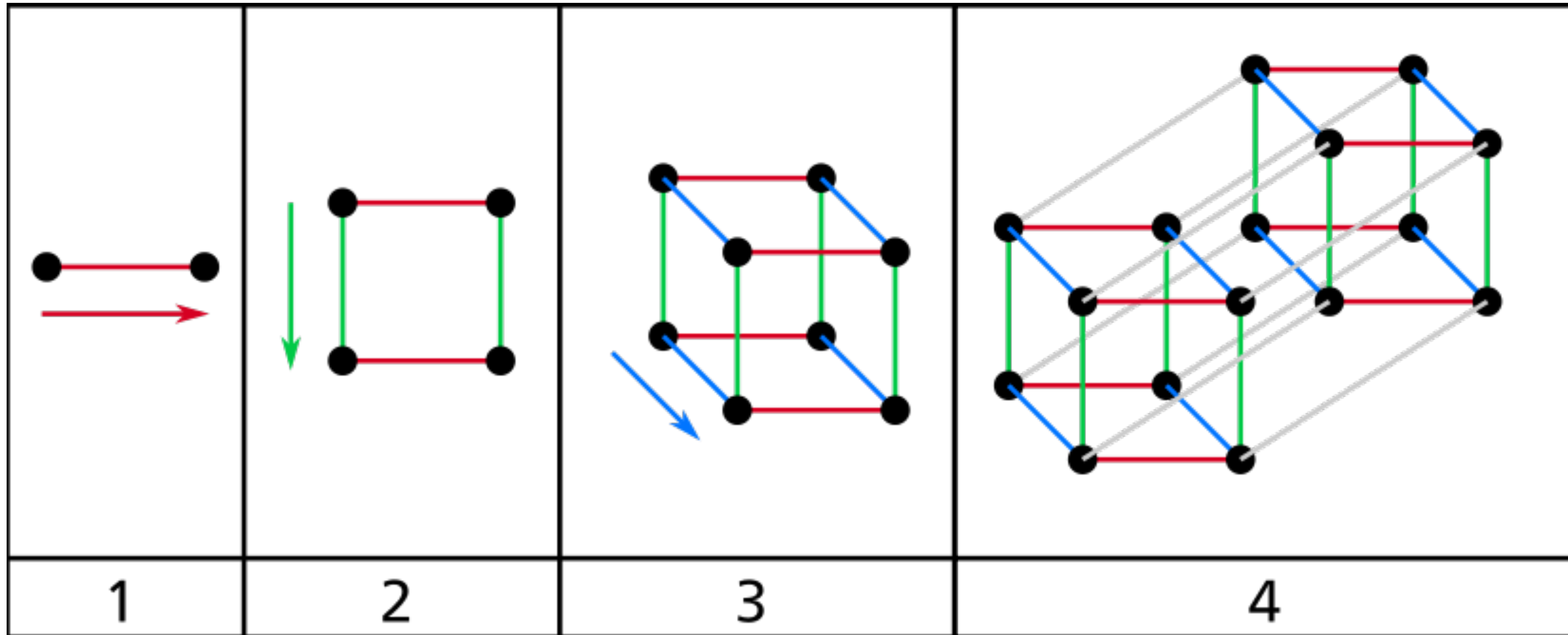


Fubini's theorem:

$$\int_{X \times Y \times Z} f(x, y, z) \, d(x, y, z) = \int_Z \left(\int_Y \left(\int_X f(x, y, z) \, dx \right) dy \right) dz = \dots$$

The curse of dimensionality

Sampling a function on a regular grid becomes completely impractical in higher dimensions.



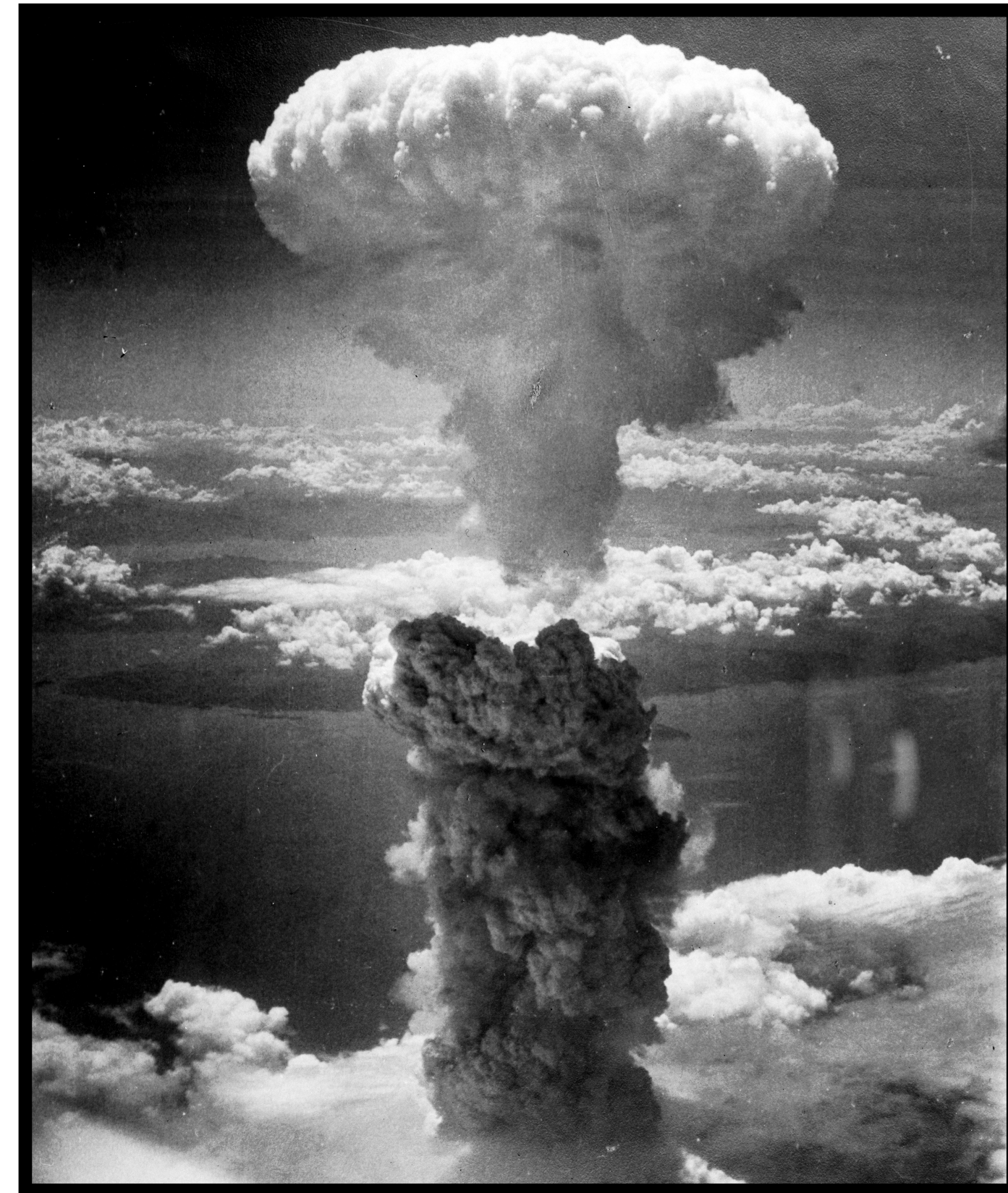
A 100-dimensional cube has
1267650600228229401496703205376 corners

(!!!)

Monte Carlo Integration

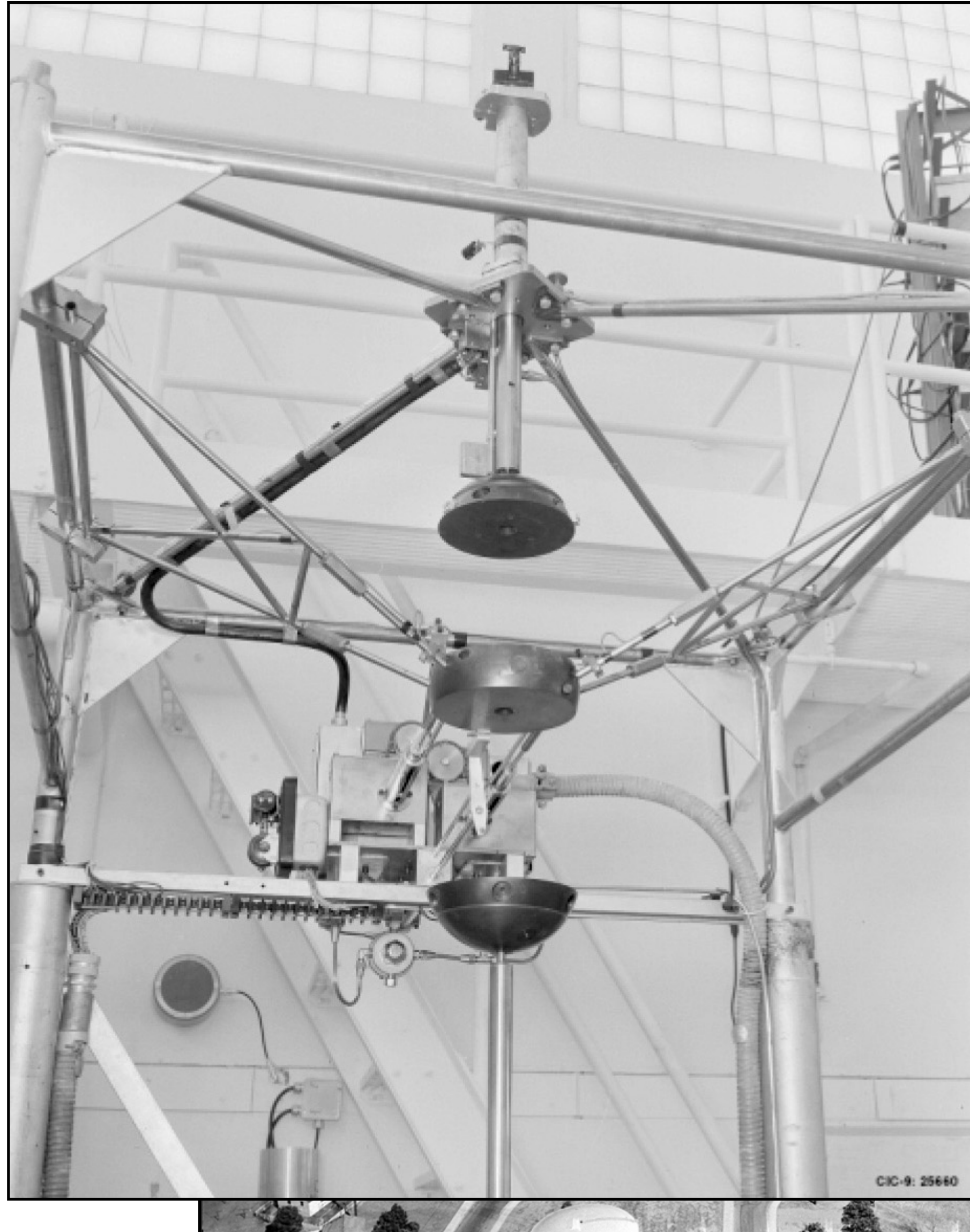
History of the Monte Carlo method

- Developed in the 1940s in the context of the development of the atomic bomb
- General & very easy to implement.
- Uses randomness to simulate many possible realizations of a complex process
- Very slow convergence

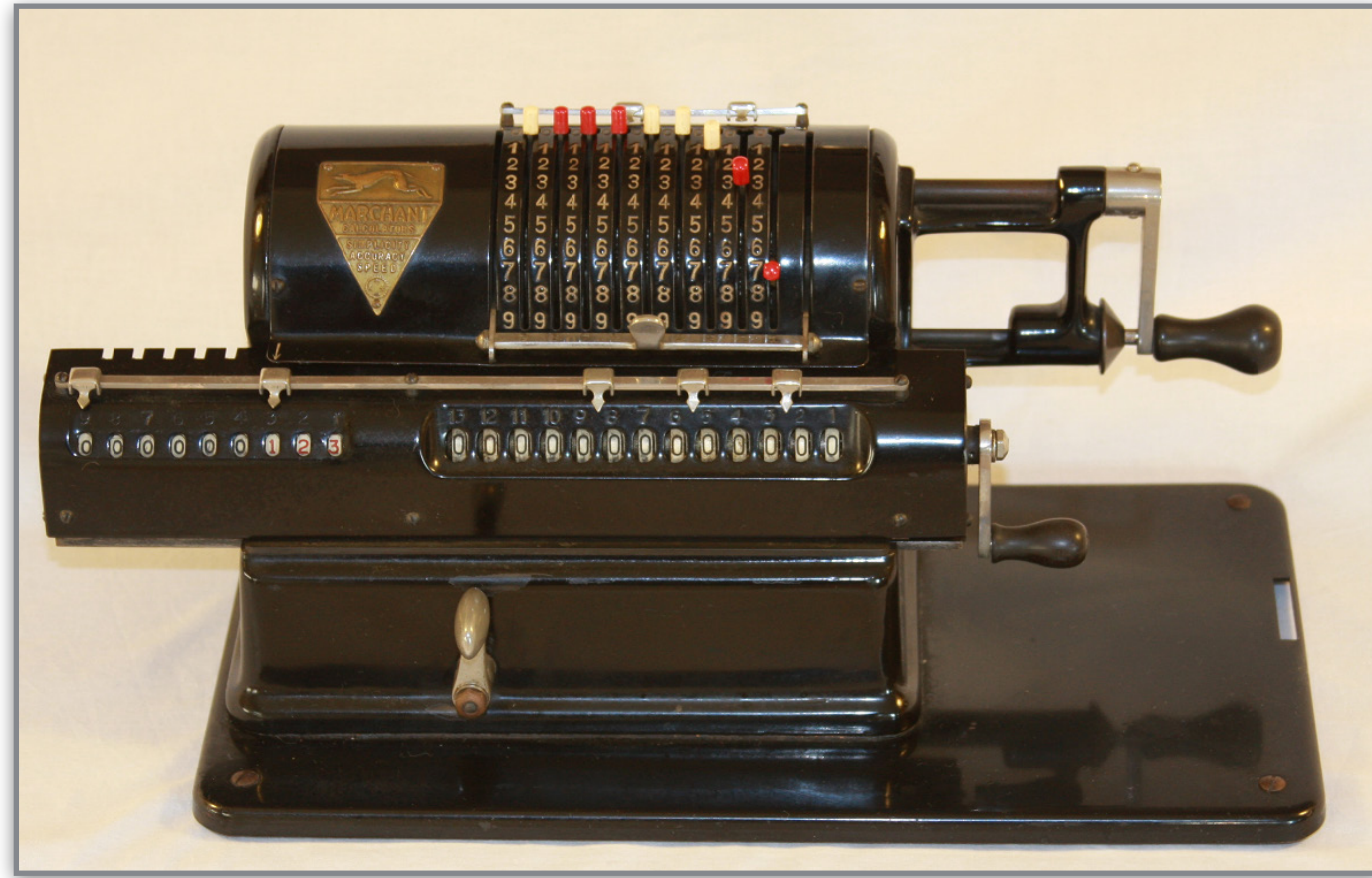


The Manhattan Project

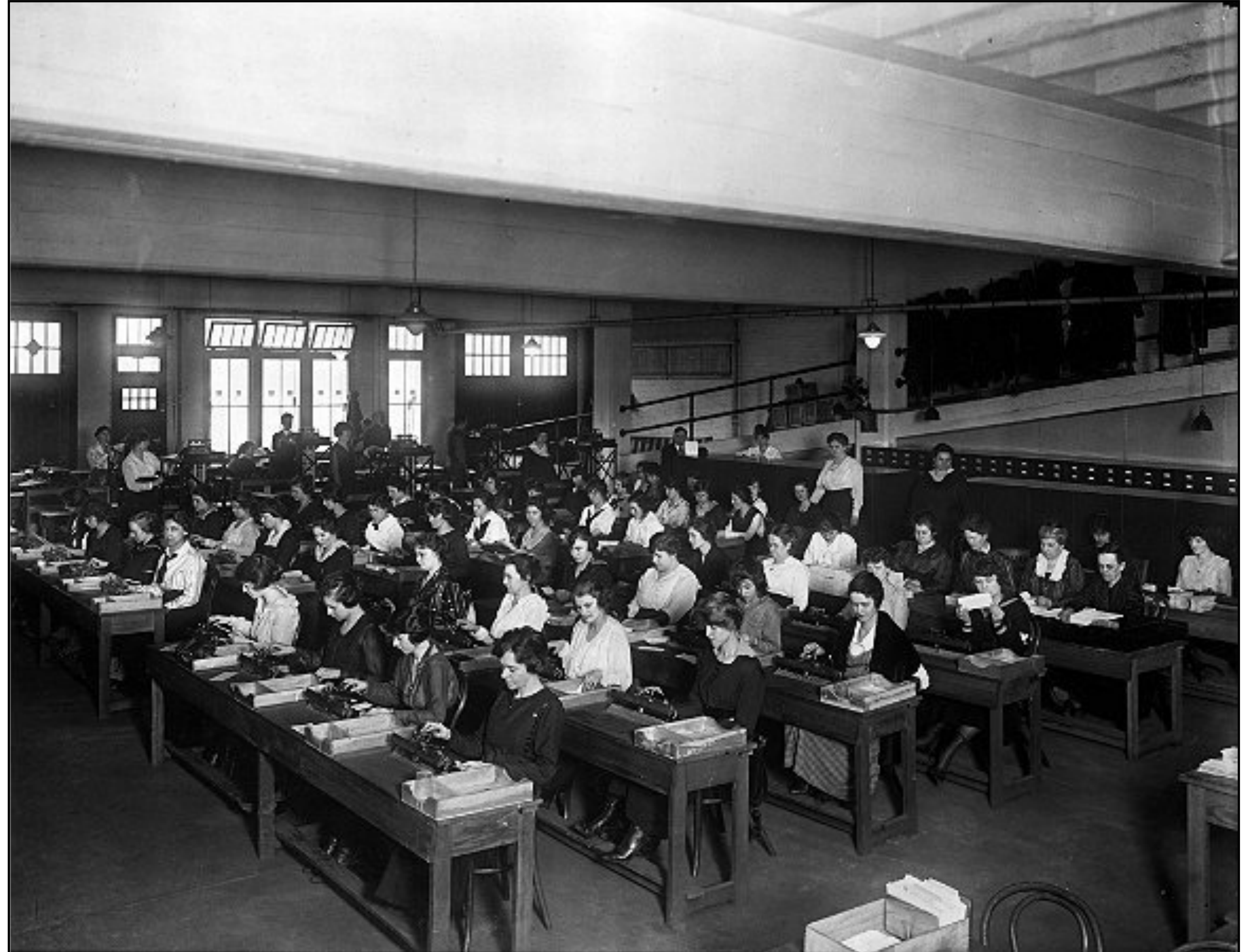
[Godiva device, Wikipedia commons]



Human computers



Marchant desk calculator



Stanisław Ulam's hospital stay



Lose



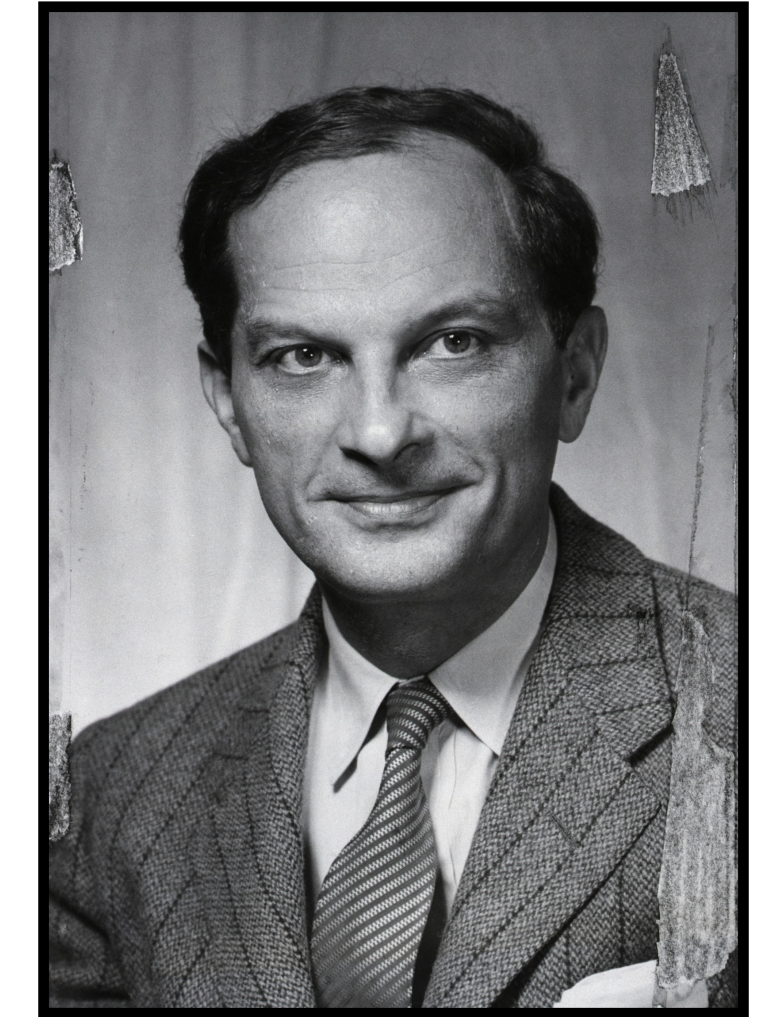
Win



Win



Lose



Stanisław Ulam

What's the chance of winning with a properly shuffled deck?

$$P = \lim_{n \rightarrow \infty} P_n \quad \text{where} \quad P_n = \frac{1}{n} \sum_{i=1}^n \begin{cases} 1, & \text{game } i \text{ is won,} \\ 0, & \text{game } i \text{ is lost} \end{cases}$$

Recap: Birthday Paradox

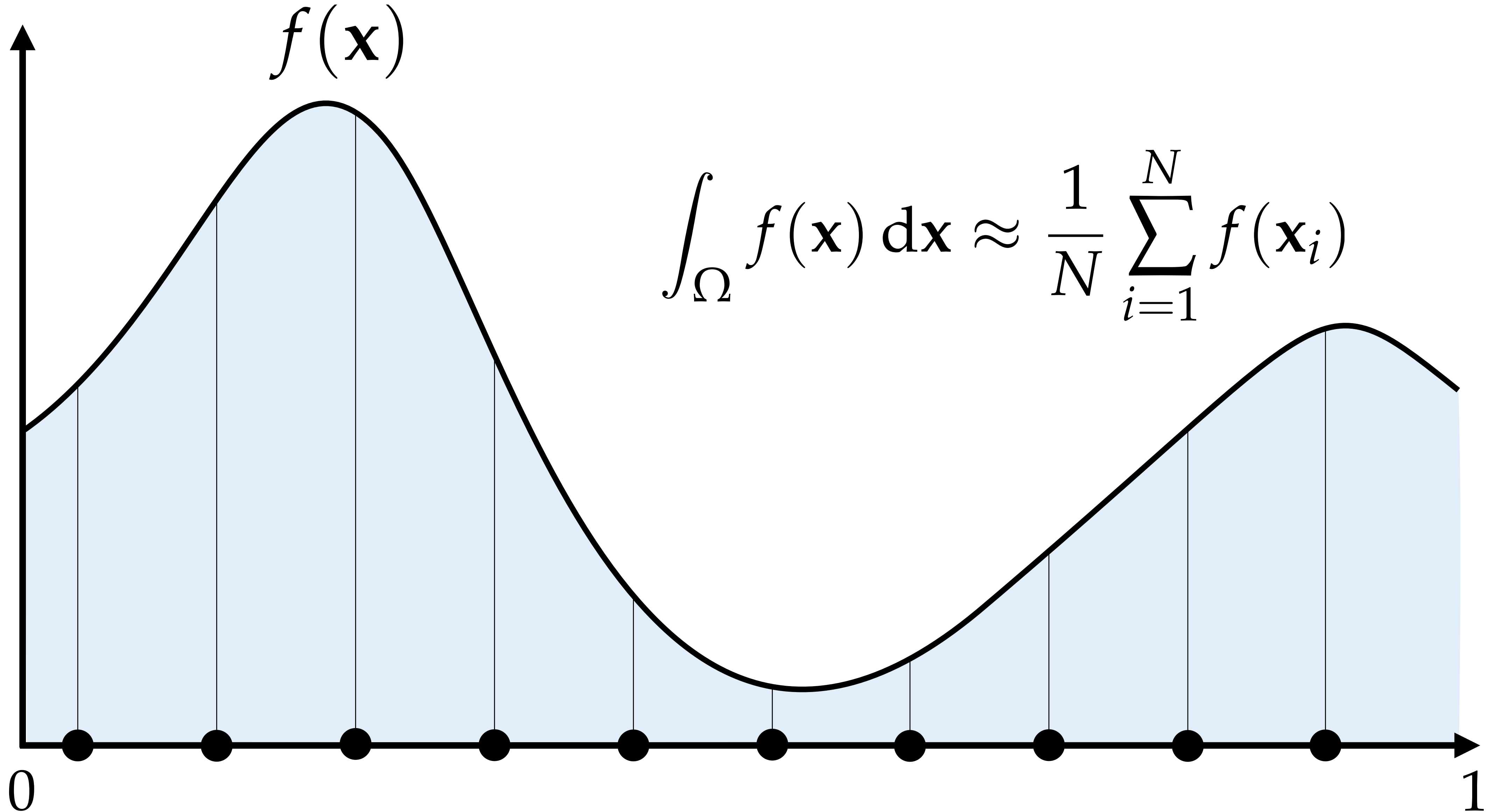
You have **already used** a Monte Carlo method in CS328!

```
In [7]: # For n people, compute an approximation of the probability that two people share the same birthday, using K iterations
def birthday_paradox(n, K):
    s = 0 # Keep track of how often the statement is true

    # Perform K iterations of the same experiment.
    for it in range(K):
        dates = [rnd.randint(0, 365) for i in range(n)]
        if len([x for x in dates if dates.count(x) > 1]) > 0:
            s += 1

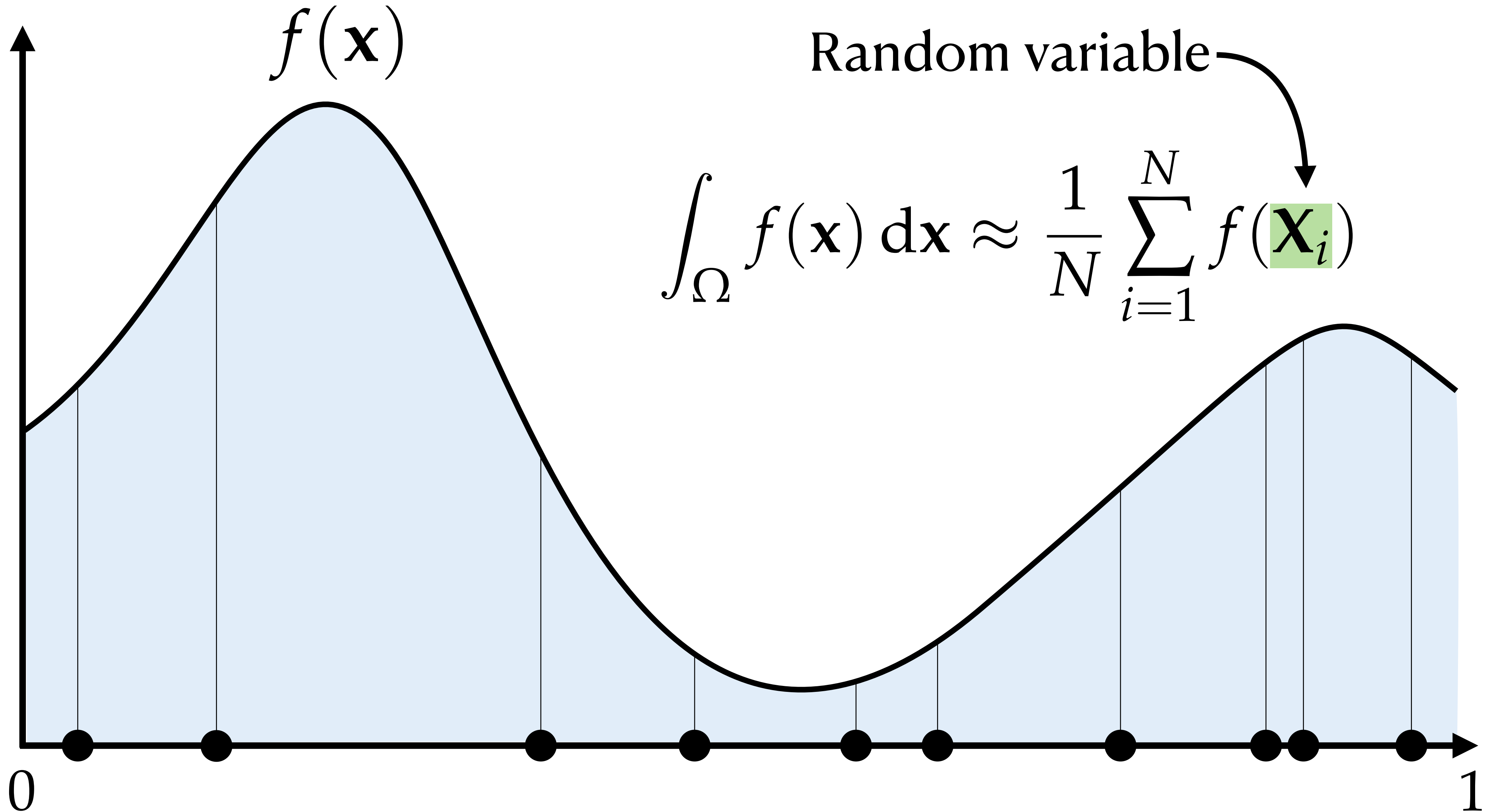
    # Return average probability
    return s / K
```

Recap: Riemann sums & quadrature



$$\int_{\Omega} f(\mathbf{x}) \, d\mathbf{x} \approx \frac{1}{N} \sum_{i=1}^N f(\mathbf{x}_i)$$

Monte Carlo integration



Does Monte Carlo integration work?

$$\cancel{\frac{1}{N} \sum_{i=1}^N f(\mathbf{x}_i)} \stackrel{?}{\approx} \int_{\Omega} f(\mathbf{x}) \, d\mathbf{x}$$

$$E \left[\frac{1}{N} \sum_{i=1}^N f(\mathbf{x}_i) \right] = \frac{1}{N} \sum_{i=1}^N E [f(\mathbf{x}_i)]$$

Linearity of the expected value

$$= \frac{1}{N} \sum_{i=1}^N \int_{\Omega} f(\mathbf{x}) p_{\mathbf{x}_i}(\mathbf{x}) \, d\mathbf{x}$$

Expectation over the continuous set Ω of possible outcomes

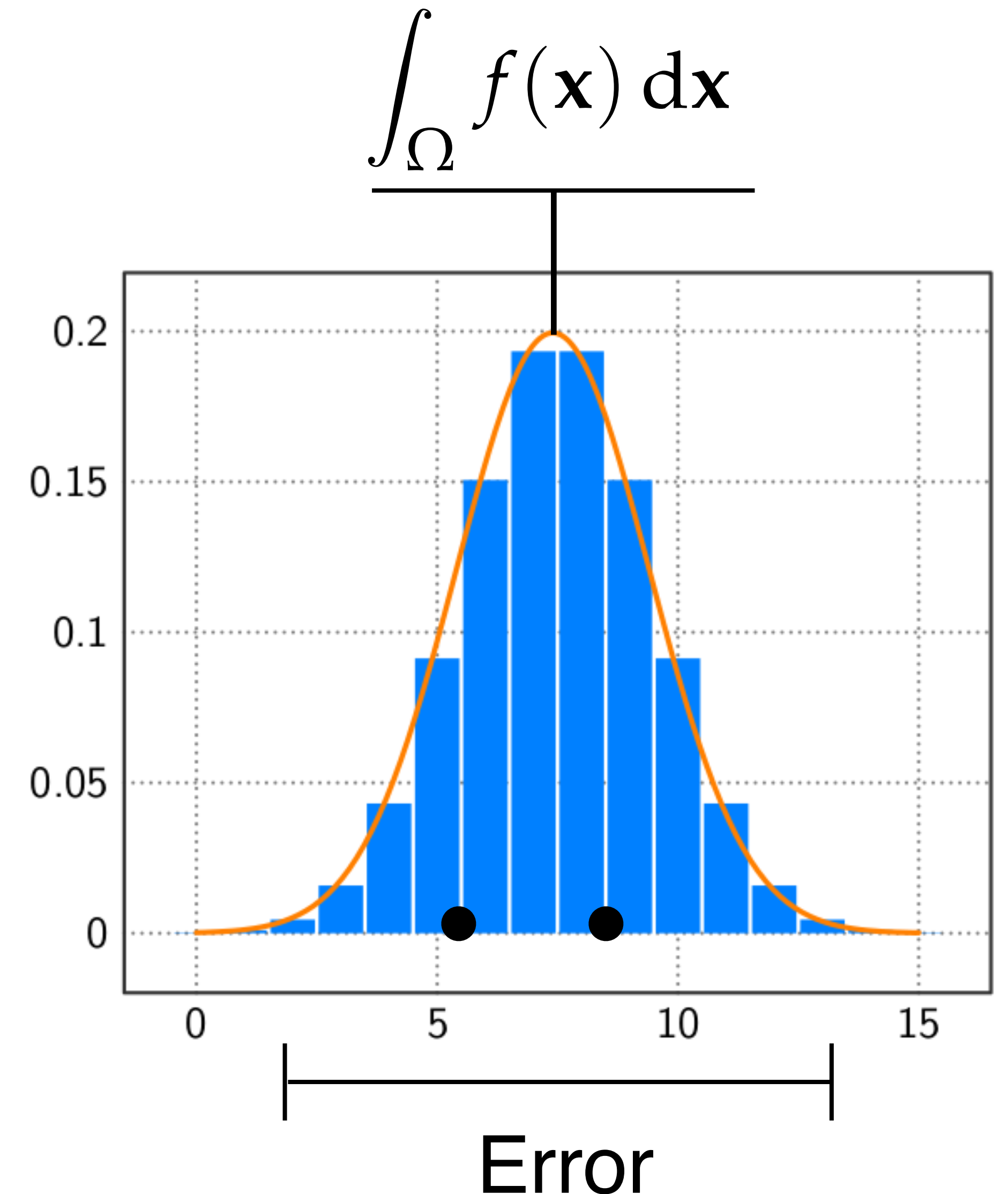
(Suppose that $p_{\mathbf{x}_i} \equiv 1$ and volume of $\Omega \equiv 1$)

$$= \int_{\Omega} f(\mathbf{x}) \, d\mathbf{x}$$

Uniform distribution

Characteristics

- Result obtained by averaging many samples
- **Central limit theorem** says: the result will tend to a normal distribution.
- Previous slide showed that the distribution is centered around the correct answer.
- **But:** algorithm will give a random answer, so there is always some error. This can be characterized using the variance.



How well does it work?

Assuming that the random variables X_i are independent:

$$\text{Var} \left[\frac{1}{N} \sum_{i=1}^N X_i \right] = \frac{1}{N} \text{Var}[X] = \text{constant}$$

Dimension doesn't influence
the convergence rate!

the convergence rate!

This means Error reduction proportional to $\sim \frac{1}{\sqrt{N}}$ i.e. increase samples 4 x to reduce error by half!

A word of caution

Monte Carlo is an extremely bad method. It should be used only when all alternative methods are worse.

- Alan Sokal

Rough guideline:

1-3 dimensions: quadrature & adaptive quadrature

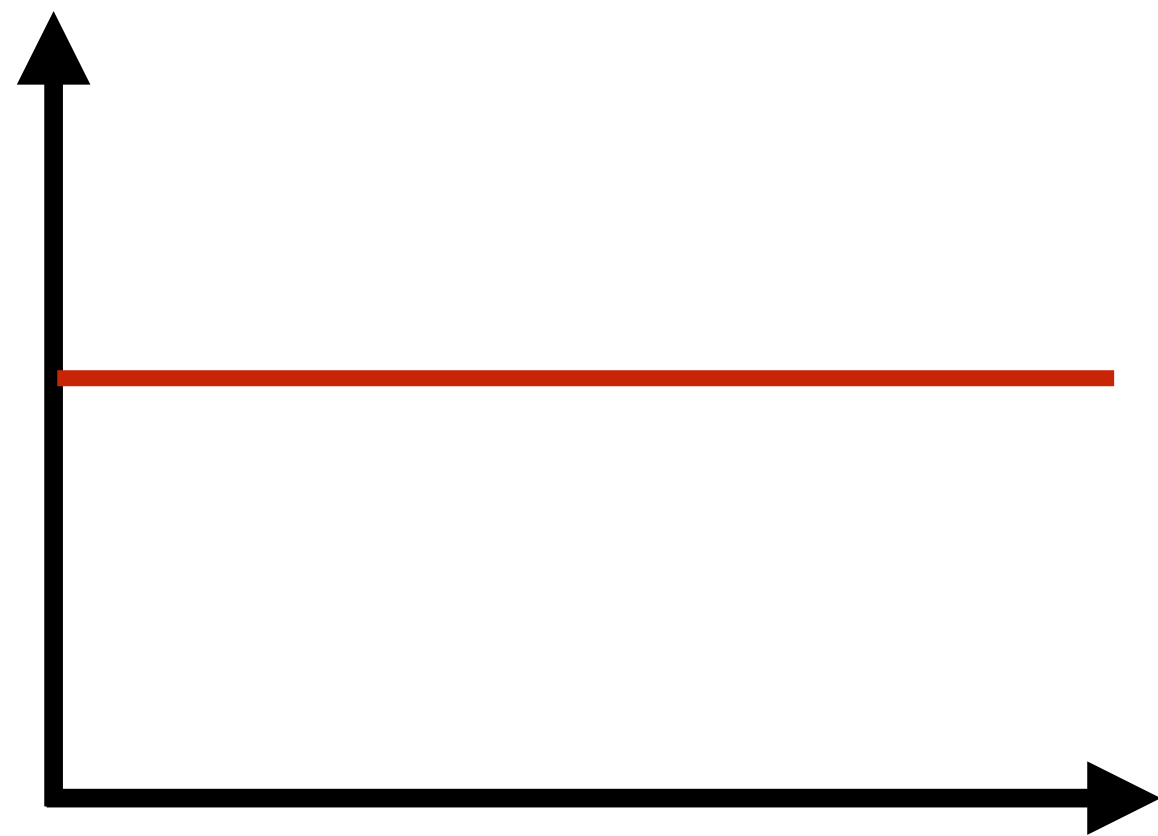
4 dimensions+: Monte Carlo integration

Demo time

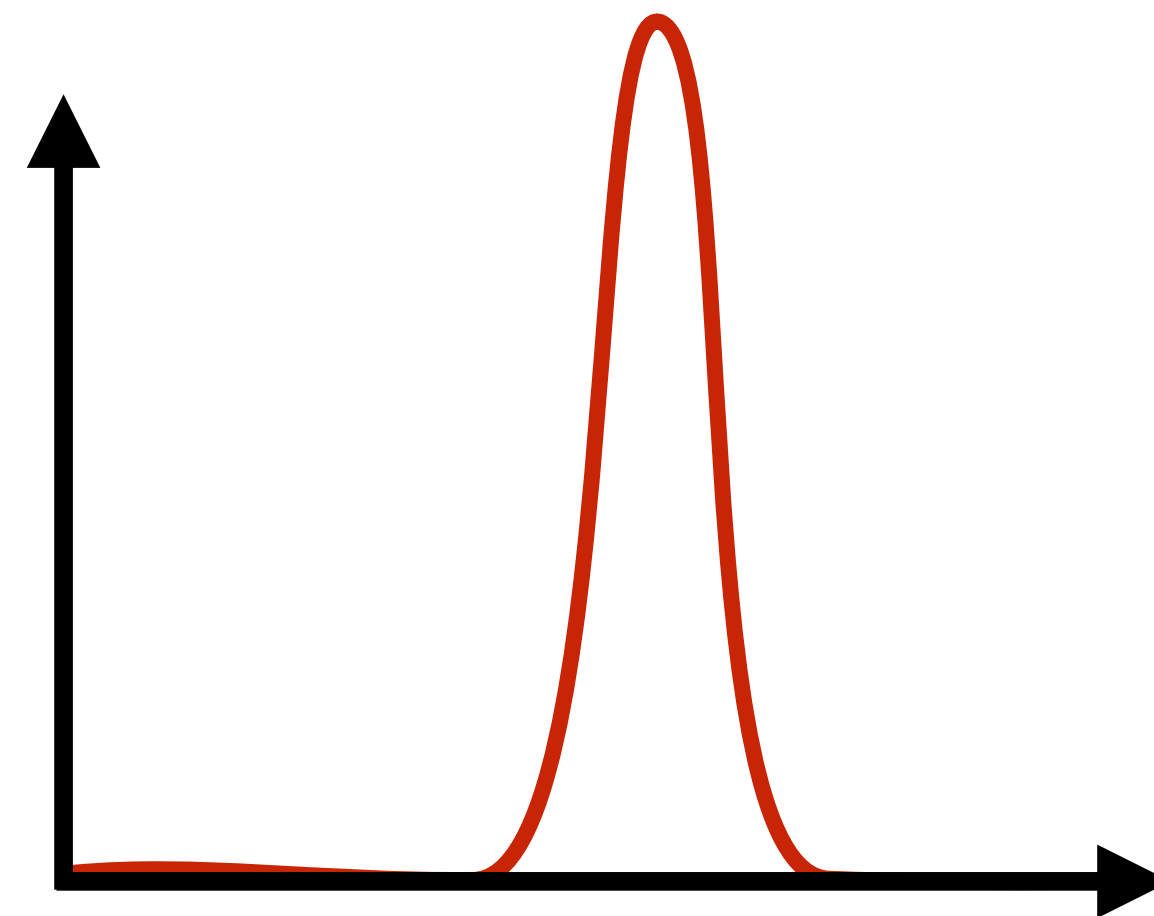
How much error do we expect?

$$\text{Error} \approx \sqrt{\frac{1}{N} \text{Var}[f(\mathbf{X}_i)]}$$

How big is $\text{Var}[f(\mathbf{X}_i)]$?

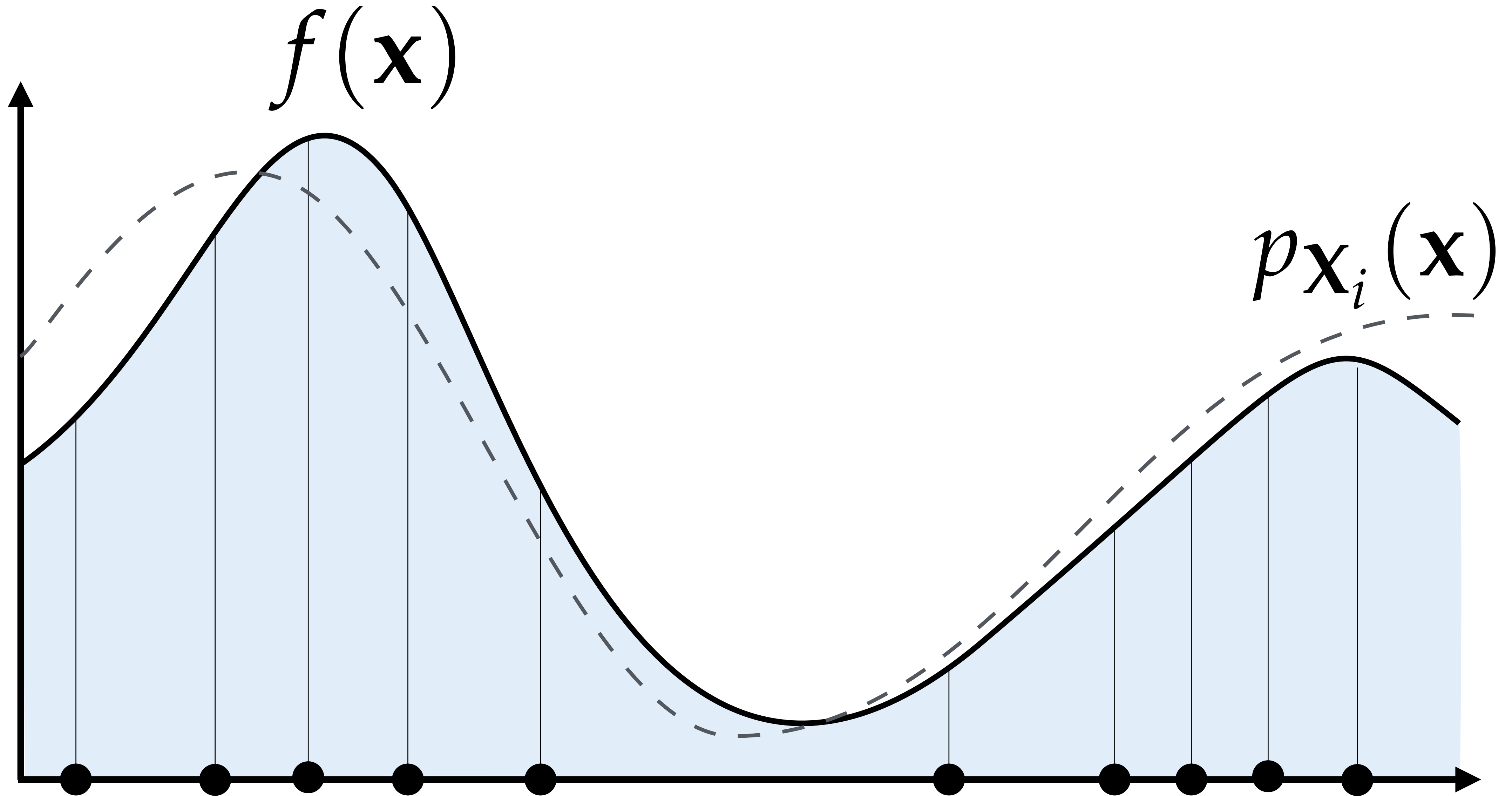


Example 1



Example 2

Importance sampling



Derivation

$$E \left[\frac{1}{N} \sum_{i=1}^N \frac{f(\mathbf{X}_i)}{p_{\mathbf{X}}(\mathbf{X}_i)} \right] = \frac{1}{N} \sum_{i=1}^N E \left[\frac{f(\mathbf{X}_i)}{p_{\mathbf{X}}(\mathbf{X}_i)} \right]$$

Linearity of the expected value

$$= \frac{1}{N} \sum_{i=1}^N \int_{\Omega} \frac{f(\mathbf{x}) p_{\mathbf{X}}(\mathbf{x})}{p_{\mathbf{X}}(\mathbf{x})} d\mathbf{x}$$

Expectation over the continuous set Ω of possible outcomes

~~(Suppose that $p_{\mathbf{X}} \equiv 1$ and Volume of $\Omega \equiv 1$)~~

~~$$= \int_{\Omega} f(\mathbf{x}) d\mathbf{x}$$~~

~~Uniform distribution~~

$$= \int_{\Omega} \frac{f(\mathbf{x}) p_{\mathbf{X}}(\mathbf{x})}{p_{\mathbf{X}}(\mathbf{x})} d\mathbf{x} \neq \int_{\Omega} f(\mathbf{x}) d\mathbf{x}$$

Importance sampling

$$E \left[\frac{1}{N} \sum_{i=1}^N \frac{f(\mathbf{X}_i)}{p_{\mathbf{X}}(\mathbf{X}_i)} \right] = \int_{\Omega} f(\mathbf{x}) d\mathbf{x}$$

This is known as **Importance Sampling**.

Requirement: $p_{\mathbf{X}}(\mathbf{x}) > 0$ for all \mathbf{x} with $f(\mathbf{x}) \neq 0$.

How to find the sampling distribution?

- Picking a good sampling distribution p is a crucial step to effectively use Monte Carlo methods. Ideally as close as possible to f .
- The typical recipe is:
 - Start with *uniformly distributed* random numbers
 - Transform these random numbers by a sequence of mathematical operations, which changes their distribution.
 - Details depend on the application/integral.
- CS440, my master-level course about graphics will teach you all about this.

Monte Carlo methods in the film industry

← Monte Carlo noise!!!

**Next lecture:
Inverse Graphics**

(last lecture of the semester)